

THE CHINESE UNIVERSITY OF HONG KONG
Department of Mathematics
MATH4030 Differential Geometry
7 November, 2024 Tutorial

$X: U \rightarrow S_1$
 $Y: V \rightarrow S_2$

1. A pair of surfaces S_1, S_2 are called conjugate minimal surfaces if they are covered by isothermal parameterisations X, Y such that

$$X_u = -Y_v, \quad X_v = Y_u.$$

That is, they satisfy the Cauchy-Riemann equations. By PDE, this means that they are also harmonic and therefore S_1, S_2 are minimal. Show that the surface parameterised by

$$Z_t = \cos t X + \sin t Y, t \in \mathbb{R}$$

is minimal by showing that Z_t is also isothermal and harmonic. This means that if we have a pair of conjugate minimal surfaces parameterised by X, Y , we can find a 1-parameter family of minimal surfaces Z_t that continuously interpolates between X ($t = 0$) and Y ($t = \pi/2$).

2. Compute the Christoffel symbols of a surface of revolution given by

$$X(u^1, u^2) = (f(u^2) \cos u^1, f(u^2) \sin u^1, g(u^2)).$$

3. Recall that a diffeomorphism $\varphi : S_1 \rightarrow S_2$ is an isometry if for any $p \in S_1$ and $v, w \in T_p S_1$,

$$\langle v, w \rangle_p = \langle d\varphi_p(v), d\varphi_p(w) \rangle_{\varphi(p)}.$$

Show that φ is an isometry if and only if the arc-length of any parameterised curve in S_1 is equal to the arc-length of the image curve under φ .

Discussion
at 0850

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Given: $X: U \rightarrow S_1$ Recall isothermal means
 $Y: V \rightarrow S_2$

$$[g_{uv}]_X = \begin{bmatrix} \lambda^2(u,v) & 0 \\ 0 & \lambda^2(u,v) \end{bmatrix}$$

$$[g_{\tilde{u}\tilde{v}}]_Y = \begin{bmatrix} r^2(\tilde{u},\tilde{v}) & 0 \\ 0 & r^2(\tilde{u},\tilde{v}) \end{bmatrix}$$

If X are isothermal coordinates covering S and X is harmonic,

$$\Delta X = X_{uu} + X_{vv} = 0$$

then S is minimal. (i.e. $H_S \equiv 0$).

Setup: $X_u = -Y_v, \quad X_v = Y_u$. Cauchy Riemann equations

Pf: Z_t isothermic: $Z_u = \cos t X_u + \sin t Y_u, \quad Z_v = \cos t X_v + \sin t Y_v$.

$$\begin{aligned} \langle Z_u, Z_u \rangle &= \langle \cos t X_u + \sin t Y_u, \cos t X_u + \sin t Y_u \rangle \\ &= \cos^2 t \langle X_u, X_u \rangle + 2 \cos t \sin t \langle X_u, Y_u \rangle + \sin^2 t \langle Y_u, Y_u \rangle \\ &= \cos^2 t \lambda^2 + 2 \cos t \sin t \langle X_u, X_v \rangle + \sin^2 t \lambda^2 \\ &= \lambda^2. \end{aligned}$$

$$\langle Z_v, Z_v \rangle = \lambda^2 \quad \text{similarly.}$$

$$\begin{aligned} \langle Z_u, Z_v \rangle &= \langle \cos t X_u + \sin t Y_u, \cos t X_v + \sin t Y_v \rangle \\ &= \cos^2 t \langle X_u, X_v \rangle + \sin t \cos t \langle X_u, Y_v \rangle + \sin t \cos t \langle Y_u, X_v \rangle \\ &\quad + \sin^2 t \langle Y_u, Y_v \rangle \end{aligned}$$

$$\begin{aligned}
 &= -\cos t \sin t \langle X_u, X_u \rangle + \cos t \sin t \langle X_v, X_v \rangle \\
 &= \lambda^2 (\cos t \sin t - \cos t \sin t) = 0.
 \end{aligned}$$

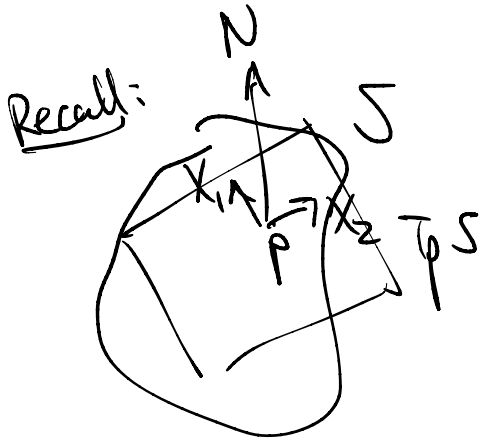
So $[g_{uv}]_Z = \begin{bmatrix} \lambda^2 & 0 \\ 0 & \lambda^2 \end{bmatrix}$ and Z is isothermic.

$$\begin{aligned}
 \Delta Z &\rightarrow Z_{uu} + Z_{vv} = \cos t X_{uu} + \sin t Y_{uu} + \cos t X_{vv} + \sin t Y_{vv} \\
 &= \cos t \Delta X + \sin t \Delta Y \\
 &= 0.
 \end{aligned}$$

Helicoid and Catenoid can be shown to be conjugate minimal surfaces.
 "associate family" of minimal surfaces.

2. Compute the Christoffel symbols of a surface of revolution given by

$$X(u^1, u^2) = (f(u^2) \cos u^1, f(u^2) \sin u^1, g(u^2)).$$



$$\text{So } \mathbb{R}^3 = \text{span} \{X_1, X_2, N\}.$$

So regarding $\partial_i \partial_j X$ as a vector in $\mathbb{R}^3$,

$$\partial_i \partial_j X = \Gamma_{ij}^1 X_1 + \Gamma_{ij}^2 X_2 + h_{ij} N.$$

Einstein summation

$$= \sum_{k=1}^2 \Gamma_{ij}^k X_k + h_{ij} N.$$

2nd f.f.

$$= \Gamma_{ij}^k X_k + h_{ij} N$$

$$\Gamma_{ij}^k = \frac{1}{2} g^{kl} (\partial_i g_{jl} + \partial_j g_{il} - \partial_l g_{ij}).$$

Pf: 1st f.f. of surface of revolution

$$g = \begin{bmatrix} f^2 & 0 \\ 0 & (f')^2 + (g')^2 \end{bmatrix} \quad g^{-1} = \frac{1}{f^2((f')^2 + (g')^2)} \begin{bmatrix} (f')^2 + (g')^2 & 0 \\ 0 & f^2 \end{bmatrix}.$$

Since g^{-1} is diagonal, we have

$$\begin{aligned} \Gamma_{11}^1 &= \frac{1}{2} \sum_{l=1}^2 g^{ll} (\partial_1 g_{1l} + \partial_1 g_{l1} - \partial_l g_{11}) \\ &= \frac{1}{2} g^{11} \partial_1 g_{11} + \frac{1}{2} g^{22} (\partial_1 g_{12} + \partial_1 g_{12} - \partial_2 g_{11}) \\ &= \frac{1}{2} g^{11} \partial_1 g_{11} \end{aligned}$$

Since ∂_1 means $\frac{\partial}{\partial u^1}$
 Since $g_{11} = f^2(u^2)$ which does not depend on u^1 .

$$\Gamma_{11}^2 = \frac{1}{2} g^{22} (\partial_1 g_{12} + \partial_1 g_{12} - \partial_2 g_{11}) = -\frac{1}{2} g^{22} \partial_2 g_{11} = -\frac{1}{2} g^{22} (2ff') \\ = \frac{-ff'}{(f')^2 + (g')^2}$$

$$\Gamma_{12}^1 = \frac{1}{2} g^{11} (\cancel{\partial_1 g_{21}^0} + \partial_2 g_{11} - \cancel{\partial_1 g_{12}^0}) = \frac{1}{2} g^{11} \partial_2 g_{11} = g^{11} ff' \\ = \frac{ff' \cancel{((f')^2 + (g')^2)}}{f^2 \cancel{((f')^2 + (g')^2)}} = \frac{f'}{f}$$

$$\Gamma_{12}^2 = 0, \quad \Gamma_{22}^1 = 0, \quad \Gamma_{22}^2 = \frac{f'f'' + g'g''}{(f')^2 + (g')^2}$$

compute K from Γ_{ij}^k, g_{ij}

3. Recall that a diffeomorphism $\varphi : S_1 \rightarrow S_2$ is an isometry if for any $p \in S_1$ and $v, w \in T_p S_1$,

$$\langle v, w \rangle_p = \langle d\varphi_p(v), d\varphi_p(w) \rangle_{\varphi(p)}.$$

Show that φ is an isometry if and only if the arc-length of any parameterised curve in S_1 is equal to the arc-length of the image curve under φ .

$\Rightarrow$: Let $\alpha : [a, b] \rightarrow S_1$ be a curve. $\varphi(\alpha)$ is a curve in S_2 .

$$\begin{aligned}
 L(\varphi(\alpha)|_{[a, b]}) &= \int_a^b |(\varphi \circ \alpha)'(t)| dt \\
 &= \int_a^b \langle d\varphi_{\alpha(t)}(\alpha'(t)), d\varphi_{\alpha(t)}(\alpha'(t)) \rangle^{\frac{1}{2}} dt \\
 &= \int_a^b \langle \alpha'(t), \alpha'(t) \rangle^{\frac{1}{2}} dt \\
 &= L(\alpha|_{[a, b]}).
 \end{aligned}$$